

DETERMINE TOPOLOGY  
SPACE

## TRANSFORM TOPOLOGY SPACE INTO CONNECTED GROUP SPACE

### FIND SOLUTION IN CONNECTED GROUP SPACE

DETERMINE DATA LINK LAYER  
PATH (LAYER 2 PATH)  
BETWEEN SOURCE DEVICE  
AND DESTINATION DEVICE BY  
TRANSFORMING SOLUTION  
BACK INTO TOPOLOGY SPACE

**FIG. 1**

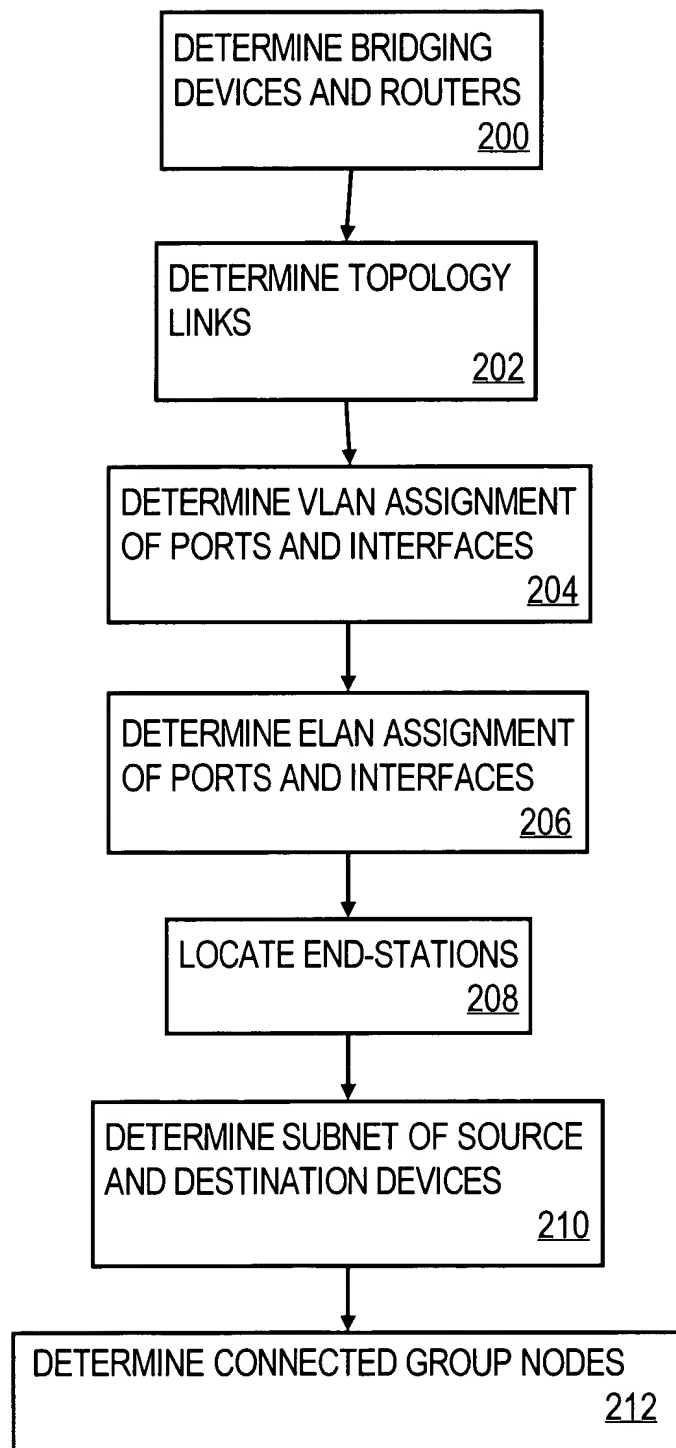
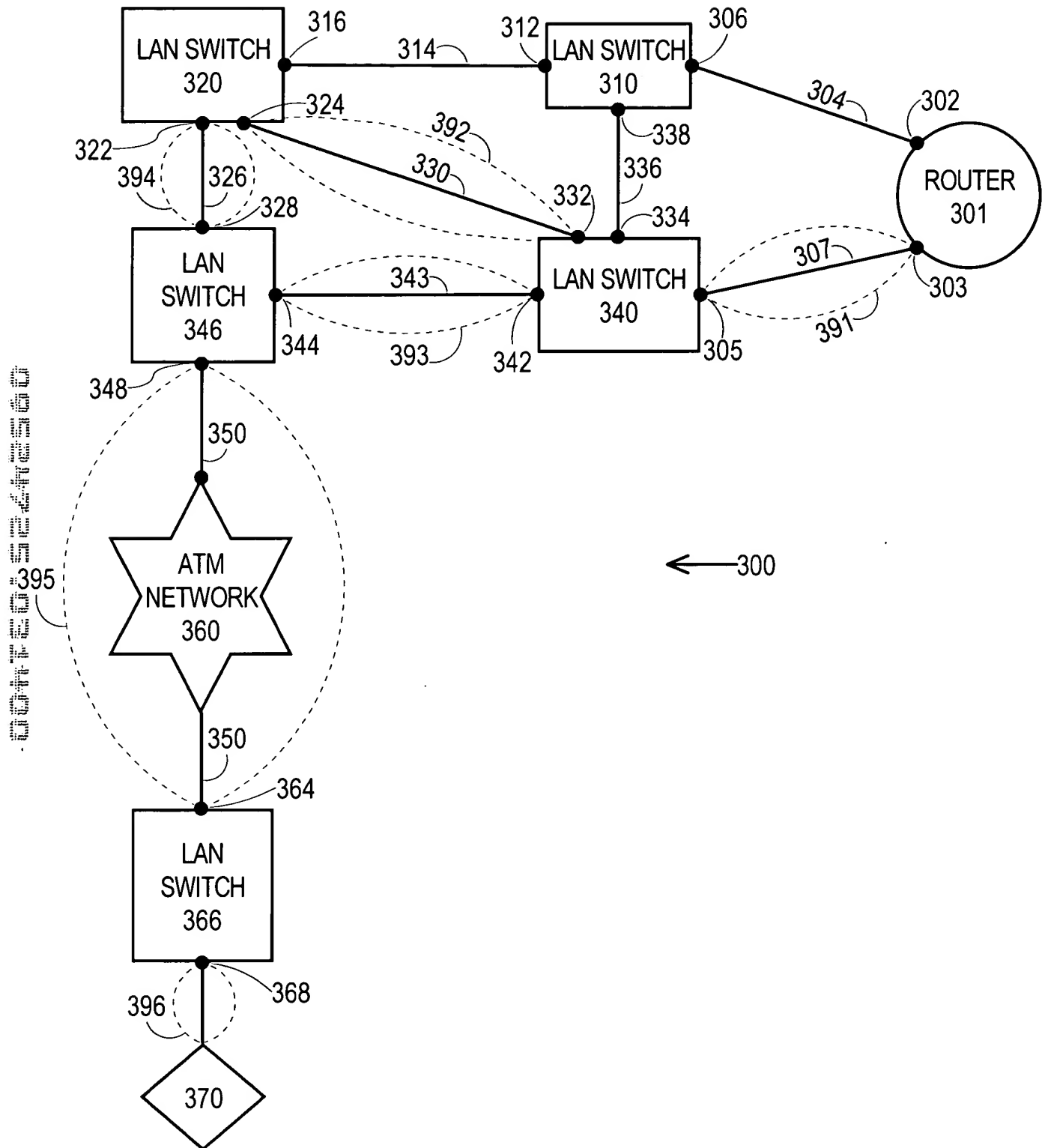


FIG. 2



**FIG. 3**

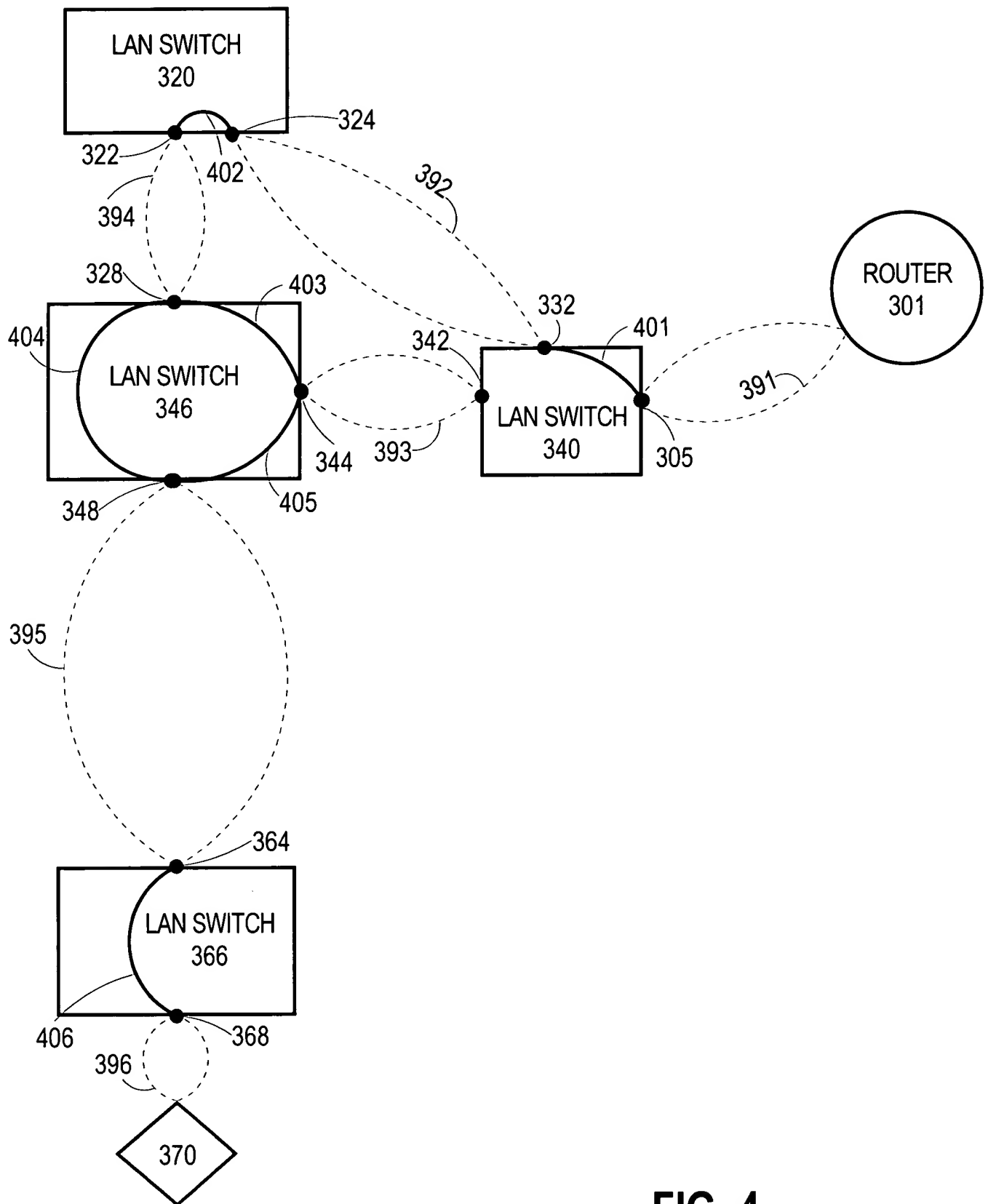
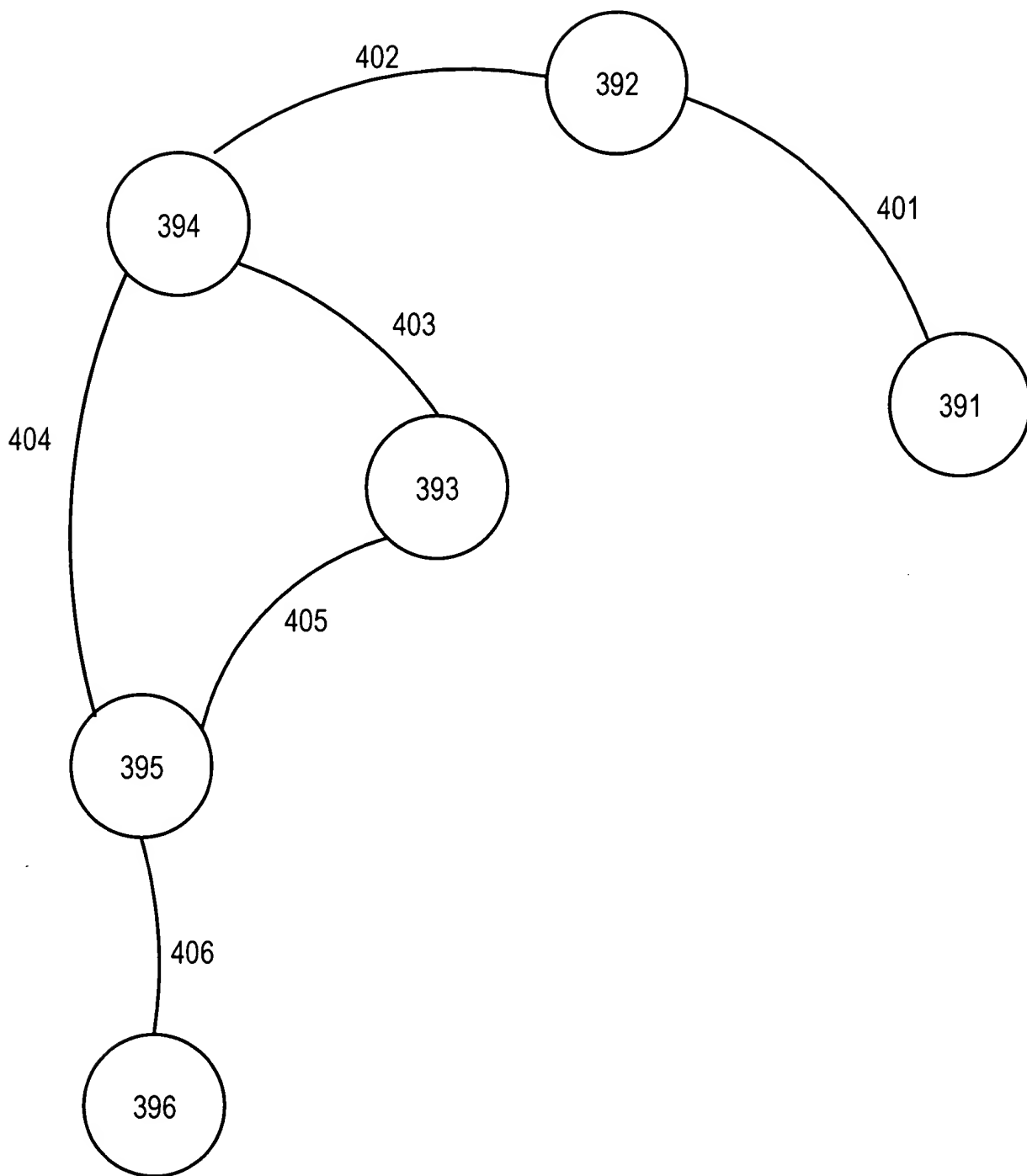
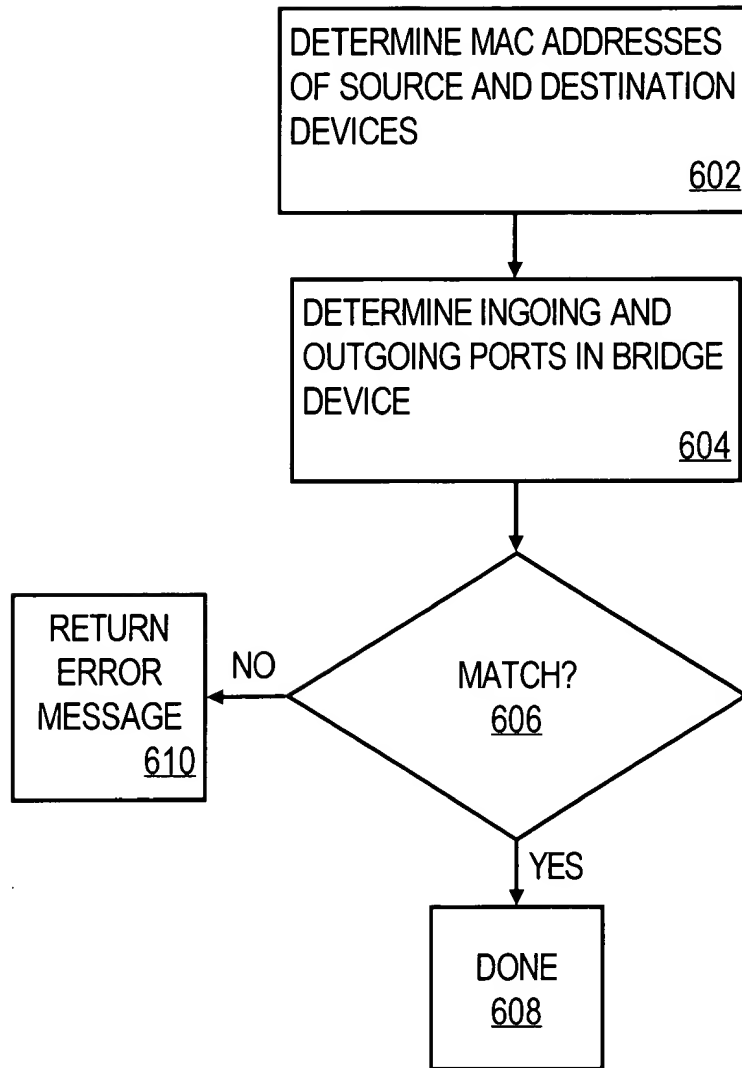


FIG. 4

Patented Mar. 24, 1992



**FIG. 5**



**FIG. 6**

FIG. 7

